# Sparse Hensel Lifting 

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#### Abstract

A new algorithm is introduced which computes the multivariate leading coefficients of polynomial factors from their univariate images. This algorithm is incorporated into a sparse Hensel lifting scheme and only requires the factorization of a single univariate image. The algorithm also provides the content of the input polynomial in the main variable as a by-product. We show how we can take advantage of this property when computing the GCD of multivariate polynomials by sparse Hensel lifting.


## 1. Introduction

Various problems on multivariate polynomials such as exact division, factorization, and greatest common divisor computation, can be solved by lifting a univariate factorization by a Hensel algorithm of some sort. Four major problems can greatly impede the efficiency of the lifting process when applied to sparse polynomials. For sake of clarity we shall discuss those problems in the context of sparse factorization, $f\left(x_{1}, \ldots, x_{v}\right)$ being the polynomial to be factored. The first problem is referred to as bad zeros problem which is observed when the univariate polynomial $f\left(x_{1}, 0, \ldots, 0\right)$ either drops in degree compared to $f\left(x_{1}, \ldots, x_{v}\right)$ or has, unlike $f$, multiple roots. Both events make lifting virtually impossible. One is forced to consider in place of $f$ the polynomial $f\left(x_{1}, x_{2}+a_{2}, \ldots, x_{v}+a_{v}\right), a_{i}$ non-zero elements from the coefficient domain. The disadvantage of this transformation is that the latter polynomial will have many more terms than $f$, in case $f$ originally was sparse. It is Zippel's [19] contribution to show how sparseness can be preserved during the lifting of the translated polynomial. The second problem is referred to as extraneous factors problem which occurs when $f\left(x_{1}, a_{2}, \ldots, a_{v}\right)$ has more factors than $f\left(x_{1}, \ldots, x_{v}\right)$ does. Then the lifted factors tend to be very dense. For certain coefficient domains such as the rationals this is unlikely to happen, in practice, though theoretical justification has only been obtained recently, cf. von zur Gathen [6] and Kaltofen [8]. The third problem is what we shall call the abundant factors problem, which has been recognized only very recently [7]. $\dagger$ The problem arises when the factorization of $f$ to be lifted consists of many polynomials. Then the intermediate linear systems created by the standard Hensel lifting techniques, described e.g. in [15], [18], and [19], have exponentially many equations in polynomially many unknowns.

[^0]Von zur Gathen's clever solution to this problem shows how polynomially many equations still "strong enough" to determine all unknowns can by selected in advance. The fourth problem is called the leading coefficient problem which results from an ambiguity in the lifting process. One can essentially impose any leading coefficient on the factors and lift, but only the correct leading coefficients will keep the intermediate results sparse. Until now, no complete algorithm seems to be described, except the heuristic by Wang [15] for rational coefficients. The main result of this paper fills this gap. Our algorithm is surprising in that it works with just the factorization of $f\left(x_{1}, a_{2}, \ldots, a_{v}\right)$ and does not require, unlike Wang's method, the factorization of the leading coefficient of $f$.

Before we discuss further properties of our leading coefficient determination procedures, we wish to point out that von zur Gathen's [7] algorithm by-passes the leading coefficient problem. However, von zur Gathen's resolution compares, in most cases, unfavorably to ours because of two reasons. First, his algorithm needs to lift a univariate polynomial whose degree is the total degree of $f$ whereas our algorithm works with a univariate polynomial whose degree is the minimum of the degrees in the individual variables. Second, von zur Gathen substitutes a linear form in three variables for the minor variable that is lifted, thus possibly cubing the number of monomials, whereas we can use a standard scheme that substitutes a linear form in just one variable.

Our leading coefficient determination algorithm is a probabilistic algorithm in the sense that the correct leading coefficients are returned only if the original evaluations are lucky, that is they do not nullify a certain polynomial derived from $f$. The algorithm invokes the sparse lifting algorithm recursively. Therefore, we will describe the sparse lifting process as well, including additional conditions on the evaluations under which this procedure will return the correct results. We will also prove that we only need to select the evaluations from a moderately large set in order to ensure that all recursive calls of our algorithms succeed with high chance. It is not an easy task to prove the correctness of the sparse lifting algorithm even if we have the leading coefficients correctly. We will also supply an entirely different and simpler proof than that given in [7].

Our leading coefficient determination algorithm has another interesting property. The content of $f$ in the main variable can be determined along with the leading coefficients. This feature allows another important application of our algorithms. We can use it for substantially improving Moses's and Yun's EZ-GCD algorithm. Instead of computing the GCD of the contents of the input polynomials, we can do away with one single recursive call to the GCD procedure.

Notation: We will use $w_{i \ldots j}$ as a short-hand for the vector $\left(w_{i}, w_{i+1}, \ldots, w_{j}\right), i \leq j$. Thus $F\left[x_{1 \ldots, v}\right]$ is the domain of polynomials in $x_{1}, \ldots, x_{v}$ over $F$. The degree of $f \in F\left[x_{1 \ldots v}\right]$ in $x_{i}, 1 \leq i \leq v$, is denoted by $\operatorname{deg}_{x_{i}}(f)$, the total degree of $f$ by $\operatorname{deg}(f)$; $\operatorname{ldcf}_{x_{1}}(f) \in F\left[x_{2} \ldots v\right]$ denotes the leading coefficient of $f$ in $x_{1}, \operatorname{cont}_{x_{1}}(f) \in F\left[x_{2} \ldots \nu\right]$ the content of $f$ in $x_{1}$ (which makes sense only if $F$ is a GCD domain). The content decomposition of $f$,

$$
f=f^{\left(x_{1}\right)} \cdots f^{\left(x_{v}\right)}, f^{\left(x_{i}\right)} \in F\left[x_{i \ldots n}\right], 1 \leq i \leq v,
$$

requires

$$
\operatorname{cont}_{x_{i}}\left(f^{\left(x_{i}\right)} \cdots f^{\left(x_{v}\right)}\right)=f^{\left(x_{i+1}\right)} \cdots f^{\left(x_{v}\right)}, 1 \leq i \leq v-1 .
$$

Notice that $f^{\left(x_{1}\right)}$ is the primitive part of $f$ in $x_{1}$. If $F$ is a field, the content decomposition is unique except for association, that is multiplication with elements in $F \backslash\{0\}$ itself. In general, we write $a \sim b$ if $a$ and $b$ from a unique factorization domain (UFD) are associates. By mon $(f)$ we denote the number of non-zero monomials in $f \in F\left[x_{1 \ldots .}\right]$, that is

$$
\operatorname{mon}(f)=\operatorname{card}(I) \quad \text { with } \quad f=\sum_{i_{1 \ldots v} \in I} c_{i_{1 \ldots v}} x_{1}^{i_{1}} \cdots x_{v}^{i_{v}}, c_{i_{1 \ldots v}} \in F \backslash\{0\}
$$

By $\mathbf{Z}$ we denote the integers and by $\mathbf{Z}^{+}=\{1,2,3, \cdots \cdot\}$.

## 2. The Newton-Hensel Lemma

In this section we present another version of the Hensel lemma. The factorization to be lifted in this lemma is allowed to have multiple factors. The special case of one multiple factor becomes Newton iteration for computing roots, which explains the choice for our title. In allowing multiplicities greater than one we have, however, weakened the Hensel lemma significantly. Existence of a lifted factorization is, in general, not guaranteed any longer, only uniqueness. It requires the deep Hilbert irreducibility theorem and its effective versions to realize that in the multivariate case we do not need that aspect of the Hensel lemma, which in the univariate case is such a crucial one.

Lemma 2.1: Let $k \in \mathbf{Z}^{+}, \phi, \gamma_{1}, \ldots, \gamma_{r} \in K[y, x] \backslash K[y], \lambda_{0}, \lambda_{1}, \ldots, \lambda_{r} \in K[y], K$ a field, $\operatorname{deg}_{y}\left(\gamma_{i}\right)<k, e_{1}, \ldots, e_{r}$ not divisible by the characteristic of $K$. Assume that
i) $\quad \lambda(y)=\operatorname{ldcf}_{x}(\phi)=\lambda_{0} \lambda_{1}^{e_{1}} \cdots \lambda_{r}^{e_{r}}, \lambda(0) \neq 0$,
ii) $\quad \lambda_{0} \gamma_{1}^{e_{1}} \cdots \gamma_{r}^{e_{r}} \equiv \phi \bmod y^{k}$,
iii) $\quad \operatorname{ldcf}_{x}\left(\gamma_{i}\right) \equiv \lambda_{i} \bmod y^{k}, 1 \leq i \leq r$,
iv) $\quad \operatorname{GCD}\left(\gamma_{i}(0, x), \gamma_{j}(0, x)\right)=1$ for $1 \leq i<j \leq r$.

Furthermore assume that there exist $\bar{\gamma}_{i} \in K[y, x]$ with $\operatorname{deg}_{y}\left(\bar{\gamma}_{i}\right)<k+1$ such that
v) $\quad \lambda_{0} \bar{\gamma}_{1}^{e_{1}} \cdots \bar{\gamma}_{r}^{e_{r}} \equiv \phi \bmod y^{k+1}$,
vi) $\quad \operatorname{ldcf}_{x}\left(\bar{\gamma}_{i}\right) \equiv \lambda_{i} \bmod y^{k+1}, 1 \leq i \leq r$,
vii) $\quad \bar{\gamma}_{i} \equiv \gamma_{i} \bmod y^{k}, 1 \leq i \leq r$.

Then the $\bar{\gamma}_{i}$ are uniquely determined.

## 3. GCD-Free Basis Construction

In the Newton-Hensel lemma we needed the assumption of pairwise relative primality on the factors we lift. If one wants to lift a factorization $g_{1} \cdots g_{r} \equiv f \bmod y$, where $\operatorname{GCD}\left(g_{i}, g_{j}\right) \nmid$ 1 , one has to refine the factorization by repeated GCD computation. We introduce the notion of GCD-free basis for this problem. We shall, however, formulate our definitions and lemmas over general unique factorization domains, though we have polynomial domains in mind.

Definition 3.1: Let $A=\left\{a_{1}, \ldots, a_{r}\right\} \subset D \backslash\{0\}, D$ a UFD. A set $B=\left\{b_{1}, \ldots, b_{s}\right\}$ is called a GCD-free basis for $A$ if
i) For all $1 \leq i<j \leq s: \operatorname{GCD}\left(b_{i}, b_{j}\right) \sim 1$.
ii) For all $1 \leq i \leq r, 1 \leq j \leq s$ there exist $e_{i j} \in \mathbf{Z}, e_{i j} \geq 0: a_{i} \sim \prod_{j=1}^{s} b_{j}^{e_{i j}}$.

Lemma 3.1: Let $A, B$ as above, $g=\operatorname{GCD}\left(a_{1}, a_{2}\right)$. Then

$$
g=\prod_{j=1}^{s} b_{j}^{\min \left(e_{1 j}, e_{2 j}\right)}
$$

The question arises whether GCD-free bases with a minimum number of elements are unique. Of course, we exclude distinctions introduced by multiplying with units. Since $\left\{b_{1}\right.$, $\left.b_{2}, \cdots\right\}$ is a basis provided $\left\{b_{1}^{2}, b_{2}, \cdots\right\}$ was one, we necessarily need an additional condition.

Definition 3.2: A GCD-free basis $B$ for $A \subset D \backslash\{0\}$ is called standard if
i) $\quad s=\operatorname{card}(B)=\min \{\operatorname{card}(C) \mid C$ is a GCD-free basis for $A\}$,
ii) For all $1 \leq j \leq s, m>1:\left\{b_{1}, \ldots, b_{j-1}, b_{j}^{m}, b_{j+1}, \ldots, b_{s}\right\}$ is not a GCD-free basis for $A$.

Lemma 3.2: A standard GCD-free basis $B$ for $A \subset D \backslash\{0\}$ is uniquely determined (except for association).

The above lemma also supplies the following algorithm.

## Standard GCD-free basis algorithm

Input: $\left.A=\left\{a_{1}, \ldots, a_{r}\right\} \subset D \backslash(f 0\} \cup U(D)\right), D$ a UFD, $U(D)$ its units.
Output: $B=\left\{b_{1}, \ldots, b_{s}\right\}$ such that $B$ is a standard GCD-free basis for $A$.
$t \leftarrow r ; c_{i} \leftarrow a_{i}$ for $i=1, \ldots, r ; I=\{1, \ldots, r\}$.
FOR $i \leftarrow 1,2, \cdots \cdot$ WHILE $(i<t)$ DO
FOR $j \leftarrow i+1, i+2, \ldots$, WHILE $(j \leq t)$ DO
IF $i \in I$ and $j \in I$ THEN

$$
\begin{array}{ll}
c_{t+1} \leftarrow \operatorname{GCD}\left(c_{i}, c_{j}\right) . & \\
\operatorname{IF} c_{t+1}+1 \mathrm{THEN} & c_{i} \leftarrow c_{i} / c_{t+1} ; c_{j} \leftarrow c_{j} / c_{t+1} . \\
& \text { IF } c_{i} \sim 1 \text { THEN } I \leftarrow I \backslash\{i\} . \\
& \text { IF } c_{j} \sim 1 \text { THEN } I \leftarrow I \backslash\{j\} . \\
& I \leftarrow I \cup\{t+1\} ; t \leftarrow t+1 .
\end{array}
$$

RETURN $\left\{b_{i} \leftarrow c_{i}\right\}_{i \in I}$.
We will compute standard GCD-free bases of univariate polynomials obtained from multivariate polynomials by evaluation. The question arises under which condition these bases are just the evaluated multivariate bases. The following lemma answers this question in the general setting.

Lemma 3.3: Let $A=\left\{a_{1}, \ldots, a_{r}\right\} \subset D \backslash(\{0\} \cup U(D)), D$ a UFD, $B=\left\{b_{1}, \ldots, b_{s}\right\}$ a standard GCD-free basis for $A$. Let $E$ be a UFD, $\phi: D \rightarrow E$ a ring homomorphism. Assume that
i) $\quad$ For all $1 \leq i \leq s: \phi b_{i} \neq 0 . \phi b_{i} \notin U(E)$, the units in $E$.
ii) For all $1 \leq i<j \leq s: \operatorname{GCD}\left(\phi b_{i}, \phi b_{j}\right) \sim 1$.

Then $\phi B=\left\{\phi b_{1}, \ldots, \phi b_{s}\right\}$ is a standard GCD-free basis for $\phi A=\left\{\phi a_{1}, \ldots, \phi a_{r}\right\}$.
Historical Note: GCD-free bases have been used by Epstein [5] to determine pseudo-multiplicative independence of sets of polynomials. Epstein insists, however, that the $b_{i}$ are squarefree, which in retrospect is an unnecessary condition. Also Epstein does not establish uniqueness of the bases. Furthermore, lemma 3.3 gives a probabilistic algorithm to determine the multiplicative relationship among polynomials, using evaluation for $\phi$. We shall not go into the details. Finally, the standard GCD-free basis algorithm can be viewed as another instance of the so-called critical-pair completion algorithms (cf. Buchberger and Loos [3]). We have not used this notion because our results turn out to be obtainable quite straight-forwardly.

## 4. The Sparse Lifting Algorithm

We now present our version of the sparse Hensel lifting procedure. The algorithm combines essentially three ideas. The first is Zippel's [19] on the preservation of sparseness by assuming that any zero coefficient in the randomly evaluated polynomial indicates a zero polynomial. The second idea is von zur Gathen's [7] on lifting factors with high multiplicities and on restricting the number of equations in the arising linear systems. The third idea is ours on computing the leading coefficients and contents by recursive application of the sparse lifting algorithm. We also prove that under certain assumptions the algorithm computes the correct result. Our proof, based on lemma 2.1, not only seems simpler than von zur Gathen's [7] but also leads to a factorization procedure for polynomials given by straight-line programs [11].

## Sparse Hensel Lifting Algorithm

Input: $f \in F\left[x_{1 \ldots v}\right], F$ a field, $a_{2}, \ldots, a_{v} \in F$, and $g_{1}, \ldots, g_{r} \in F\left[x_{1}\right] \backslash F, e_{1}, \ldots, e_{r} \in \mathbf{Z}^{+}$such that

$$
\operatorname{ldcf}_{x_{1}}(f)\left(a_{2 \ldots v}\right) \neq 0
$$

and

$$
g_{1}^{e_{1}} \cdots g_{r}^{e_{r}}=f\left(x_{1}, a_{2 \ldots v}\right), \operatorname{GCD}\left(g_{i}, g_{j}\right)=1,1 \leq i<j \leq r
$$

We make the following assumptions on $a_{2}, \ldots, a_{v}$ :
True Factors Assumptions: There exist polynomials $h_{0}, \ldots, h_{r} \in F\left[x_{1 . . . v}\right]$ such that

$$
h_{0} \sim \operatorname{cont}_{x_{1}}(f), h_{0} h_{1}^{e_{1}} \cdots h_{r}^{e_{r}}=f, h_{i}\left(x_{1}, a_{2 \ldots \nu}\right)=g_{i}, 1 \leq i \leq r
$$

Notice that the $h_{i}$ are uniquely determined.
Zero Preservation Assumption: Let $q_{i}^{\left(j_{1 . \ldots n}\right)} \in F\left[x_{n+1 \ldots v}\right]$ be the coefficient of $x_{1}^{j_{1}} \cdots x_{n}^{j_{n}}$ in $h_{i}, 1 \leq$ $i \leq r, 1 \leq n<v$. Then for all $i, n$, and $j_{1 . . . n} \in\left(\mathbf{Z}^{+} \cup\{0\}\right)^{n}$

$$
q_{i}^{\left(j_{1} \ldots n\right)} \neq 0 \text { implies } q_{i}^{\left(j_{1 \ldots n}\right)}\left(a_{n+1 \ldots v}\right) \neq 0
$$

Third, we assume that the call to the Leading Coefficient algorithm in step 1 produces the correct result. This will add more conditions for the $a_{2}, \ldots, a_{v}$.

Output: $h_{0}, \ldots, h_{r} \in F\left[x_{1 \ldots v}\right]$ satisfying $(\dagger)$.
Step 1: Call the Leading Coefficient Determination Algorithm of $\S 5$ with the above inputs. We will get back $h_{0}, l_{i}=\operatorname{ldcf}_{x_{1}}\left(h_{i}\right)$ and $g_{i 2}=h_{i}\left(x_{1}, x_{2}, a_{3 \ldots v}\right), 1 \leq i \leq r$. If $r=e_{1}=1$ then return $h_{0}$, $h_{1} \leftarrow f / h_{0}$.

Step 2: Special handling for positive characteristic.
If $\operatorname{char}(F)=p>0$ then do for all $i$ with $p \mid e_{i}$ :
Compute $\mu_{i}, v_{i} \in \mathbf{Z}^{+}$such that $e_{i}=p^{v_{i}} \mu_{i}, \operatorname{GCD}\left(p, \mu_{i}\right)=1$.
Set $g_{i 2} \leftarrow g_{i 2}^{p^{v_{i}}}, e_{i} \leftarrow \mu_{i}$.
Step 3: FOR $n \leftarrow 3, \ldots, v$ DO Step 4.
Step 4: Lift a single variable. At his moment we have polynomials $g_{i, n-1} \in F\left[x_{1 \ldots n}\right]$ with $g_{i, n-1}=$ $h_{i}\left(x_{1 . . . n-1}, a_{n \ldots v}\right)$.

Let $g_{i, n}^{(1)}=g_{i, n-1}$ for $i=1, \ldots, r$.
FOR $k \leftarrow 1,2, \cdots \cdot$ WHILE $\left(\operatorname{deg}_{x_{n}}(f)>\operatorname{deg}_{x_{n}}\left(h_{0}\right)+\sum_{i=1}^{r} e_{i} \operatorname{deg}_{y}\left(g_{i, n}^{(k)}\right)\right)$ DO Step 5.
Step 5: Lift $y=x_{n}-a_{n}$ by one degree. At this moment we have polynomials $g_{i, n}^{(k)} \in F\left[x_{1 \ldots n-1}, y\right]$ such that

$$
\begin{equation*}
g_{i, n}^{(k)}=h_{i}\left(x_{1 \ldots n-1}, y+a_{n}, a_{n+1 \ldots v}\right) \bmod y^{k} \tag{†}
\end{equation*}
$$

5.1: For $1 \leq i \leq r$ set $\hat{g}_{i}=\sum c_{i}^{\left(j_{1} \ldots n-1\right)} x_{1}^{j_{1}} \cdots x_{n-1}^{j_{n-1}}$ where the $c_{i}^{\left(j_{1}, \ldots n-1\right)}$ are unknown coefficients and the summation is taken over all vectors $j_{1 \ldots n-1}$ such that the coefficient of the monomial $x_{1}^{j_{1}} \ldots$. $x_{n-1}^{j_{n-1}}$ in $g_{i, n-1}$ is not zero.
5.2. For each exponent vector $j_{1 \ldots n-1}$ such that $x_{1}^{j_{1}} \cdots x_{n-1}^{j_{n-1}} y^{k}$ occurs as a monomial in $l_{i}\left(x_{1 \ldots n-1}\right.$, $\left.y+a_{n}, a_{n+1 \ldots v}\right)$ with non-zero coefficient, replace $c_{i}^{\left(j_{1} \ldots n-1\right)}$ by this non-zero field element.
5.3: In the following we use the set $E_{n-1}^{(k)}$ of $n-1$-dimensional exponent-vectors whose initialization we shall discuss in a moment. For all $m_{1 \ldots n-1} \in E_{n-1}^{(k)}$ collect the coefficients of the monomials $x_{1}^{m_{1}} \cdots x_{n-1}^{m_{n-1}} y^{k}$ in
$f\left(x_{1 \ldots n-1}, y+a_{n}, a_{n+1 \ldots v}\right)-h_{0}\left(x_{1 \ldots n-1}, y+a_{n}, a_{n+1 \ldots v}\right) \prod_{i=1}^{r}\left(g_{i, n}^{(k)}+\hat{g}_{i} y^{k}\right)^{e_{i}}$.
We will prove in theorem 4.1 that these coefficients are linear forms in the $c_{i}^{\left(j_{1 . \ldots n-1}\right)}$ which have a unique solution in $F$. Now we concern ourselves with the initialization of $E_{2}^{(1)}$. In that case we simply collect all non-zero monomials occurring in the expansion of $(*)$, whose exponent-vectors constitute $E_{2}^{(1)}$. Notice that the expansion of $(*)$ can contain exponentially many non-zero monomials. The set $E_{n-1}^{(k)}$ will restrict us to polynomially many equations which are still "strong enough" (in the terminology of [7]) to determine all unknowns.
5.4: Compute the solution for the arising linear system, evaluate the $\hat{g}_{i}$ at that solution and set $g_{i, n}^{(k+1)} \leftarrow g_{i, n}^{(k)}+\hat{g}_{i} y^{k}$.
5.5: If $k=1$ we compute $E_{n-1}^{(2)}=E_{n-1}^{(3)}=\cdots$ as follows. Determine in the linear system solved in step 5.4 a maximal set of linearly independent homogeneous equations. Assign to $E_{n-1}^{(\kappa)}, \kappa \geq 2$, the set of the exponent-vectors $m_{1 \ldots n-1}$ of the monomials $x_{1}^{m_{1}} \cdots x_{n-1}^{m_{n-1}} y^{k}$ corresponding to those equations.

Step 4 cont.: Back translate: $g_{i, n} \leftarrow g_{i, n}^{(k)}\left(x_{1 \ldots n-1}, x_{n}-a_{n}\right)$.
Set $E_{n}^{(1)}=\left\{\left(m_{1 \ldots n-1}, d\right) \mid m_{1 \ldots n-1} \in E_{n-1}^{(k)}, 0 \leq d \leq \operatorname{deg}_{x_{n}}(f)\right\}$.
Step 2 cont.: For each $i$ with $e_{i}=\mu_{i}$ replace $g_{i, v}=\sum b_{i}^{\left(j_{1 \ldots v}\right)} x_{1}^{j_{1}} \cdots x_{v}^{j_{v}}, b_{i}^{\left(j_{1 \ldots v}\right)} \in F$, by $\sum\left(b_{i}^{\left(j_{1 . . v}\right)} x_{1}^{j_{1}} \cdots x_{v}^{j_{v}}\right)^{1 / p^{v_{i}}}$. It follows from our assumptions that $p^{v_{i}} \mid j_{n}, 1 \leq n \leq v$, and that $\left(b_{i}^{\left(j_{1} \ldots v\right)}\right)^{1 / p^{v_{i}}} \in F$. Here we must also assume that we can effectively compute $p$-th roots in $F$.

Step 6: Return $h_{0}, h_{i} \leftarrow g_{i, v}$ for $1 \leq i \leq r$.
Remark 1: It might be unclear why we do not factor out the content $h_{0}$ of $f$ before lifting or why we do not compute the squarefree factors of $g_{i}$ and lift them with respect to the squarefree part of $f$. The answer is that then some intermediately needed polynomials such as the primitive or squarefree part of $f$ or a squarefree factor of $g_{i}$ may become dense, although the final $h_{i}$ still turn out to be sparse. Following are some examples in which these intermediate factors have super-polynomially more non-zero monomials.

Example: Let

$$
f_{1}\left(x_{1}, \ldots, x_{v}\right)=\prod_{i=2}^{v}\left(x_{i}-1\right) \prod_{i=2}^{v}\left(x_{1}-\sum_{j=0}^{d} x_{i}^{j}\right)
$$

Then $\operatorname{mon}\left(f_{1}\right) \leq 4^{v-1}$ whereas $\operatorname{mon}\left(f_{1}^{\left(x_{1}\right)}\right) \geq(d+1)^{v-1}$. Let

$$
f_{2}\left(x_{1}, \ldots, x_{v}\right)=\prod_{i=2}^{v}\left(\sum_{j=0}^{d} x_{1}^{j} x_{i}^{d-j}\right) \prod_{i=2}^{v}\left(x_{1}-x_{i}\right)^{2} .
$$

Then $\operatorname{mon}\left(f_{2}\right) \leq 4^{\nu-1}$ whereas the squarefree factor with multiplicity 1 has $(d+1)^{v-1}$ monomials. Finally, let

$$
f_{3}\left(x_{1}, \ldots, x_{v}\right)=\prod_{i=2}^{v}\left(\left(\sum_{j=0}^{d} x_{1}^{j} x_{i}^{d-j}\right)^{2}+x_{1}\right) \prod_{i=2}^{v}\left(x_{1}-x_{i}\right)^{2} .
$$

Then $\operatorname{mon}\left(f_{3}\right) \leq 5^{v-1}$ whereas the squarefree part of $f_{3}$ has at least $(d+1)^{v-1}$ monomials.
One could argue, however, that the above cases are pathological and normally factors tend to have fewer monomials. Under that hypothesis it is, of course, more efficient to lift the squarefree factors of the $g_{i}$. Finally, we wish to remark that we conjecture that powers of dense polynomials must be dense.

Remark 2: We described our algorithm for coefficients from a field. If we wish to lift over a unique factorization domain, such as the integers, it is possible to avoid working in the quotient field, e.g., the rationals. First we note the following version of Gauss's lemma, a generalization of which to algebraic number fields is proven in [9].

Lemma 4.1: We call a polynomial $f=\sum_{i_{1 \ldots v} \in I} c_{i_{1 . . v}} x_{1}^{i_{1}} \cdots x_{v}^{i_{v}} \in D\left[x_{1 . . . v}\right], D$ a UFD, coefficient primitive iff its coefficient content $\operatorname{GCD}_{i_{1 . . . v} \in I}\left(c_{i_{1 . . . v}}\right) \sim 1$. Then the product of two coefficient primitive polynomials is coefficient primitive.

Thus, we can first make $f$ coefficient primitive and then compute coefficient primitive $h_{0}$ , $\ldots, h_{i}$ such that $h_{i}\left(x_{i}, a_{2 \ldots v}\right) \sim g_{i}, 1 \leq i \leq r$. This means, of course, that the leading coefficient algorithm can only determine the coefficient primitive parts of $\operatorname{ldcf}_{x_{1}}\left(h_{i}\right)$. Using these parts the solution to $\left(^{*}\right)$ can become a vector of quotients. However, Bareiss's [1] exact division algorithm for solving linear systems can be modified, using the coefficient content of $\operatorname{ldcf}_{x_{1}}(f)$, to compute the $h_{i}$ by ring operations in $D$ and exact divisions. We hope the reader will not find it too difficult to work out the details.

Remark 3: A special case of our algorithm occurs when $r=1$. Then the algorithm computes the sparse $e_{1}$-st root of a sparse polynomial polynomial $f$. Closer inspection reveals that then the algorithm performs a sparse version of Newton iteration, which is normally explicitly coded for various other problems.

Remark 4: Though it is quite unlikely that our assumptions are violated provided the $a_{i}$ are randomly selected from a sufficiently large sample set, as we will establish in §6, we want to note how such an exceptional situation can be detected. It is clear that one always can check the final answer by multiplying the results together. Von zur Gathen [7] even suggests to randomly evaluate the results to get great confidence in the correctness of the answer, but to avoid the sometimes
costly multiplication. It is also clear that if the linear system computed in Step 5.3 turns out to be singular, an assumption, most probably the zero preservation assumption, must be violated. If we use the exact division version (see remark 2) and an arising division is not exact, most probably we do not lift true factors. Finally, if the intermediate $g_{l, n}$ are not sparse, as we might suspect they should be, we either have the wrong leading coefficients or false factor images.

Now we present the correctness of the sparse lifting algorithm.
Theorem 4.1 (Main Theorem on Sparse Lifting): In the Sparse Hensel Lifting algorithm the coefficients of all monomials $x_{1}^{m_{1}} \cdots x_{n-1}^{m_{n-1}} y^{k}$ in $\left(^{*}\right)$ are linear forms in the unknowns $c_{i}^{\left(j_{1 \ldots n-1}\right)}$. Furthermore, under the true factors and zero preservation assumptions and the provision that Step 2 computes the correct leading coefficients, the derived linear system has a unique solution.

## 5. The Leading Coefficient Algorithm

It is crucial for the sparse lifting algorithm to work properly that the correct leading coefficients are know beforehand. In this section we show how they can be computed using the sparse lifting algorithm recursively on polynomials in one less variable. The main idea is quite simple. We determine a bivariate factorization of $f\left(x_{1}, x_{2}, a_{3} \ldots v\right)$ and lift the leading coefficients of that factorization with respect to the leading coefficient of $f$. Two problems arise. First, the leading coefficients of the factors may not contain $x_{2}$ at all. Thus we must try all factorizations of $f\left(x_{1}\right.$, $\left.a_{2 \ldots n-1}, x_{n}, a_{n+1 \ldots v}\right)$. Second, the leading coefficients of the bivariate factors may have common GCDs. Thus we must compute a standard GCD-free basis for them. It is more or less incidental that the whole mechanism also produces the content of $f$.

## Leading Coefficient and Content Determination Algorithm

Input: As in algorithm 1.
In addition to the true factors assumption we make the following assumptions on $a_{2}, \ldots, a_{v}$.
True leading terms assumption: Let $\lambda_{0}=h_{0}, \lambda_{i}=\operatorname{ldcf}_{x_{1}}\left(h_{i}\right), 1 \leq i \leq r$, where $h_{0}, \ldots, h_{r}$ are the outputs of the Sparse Hensel Lifting algorithm. Let

$$
\lambda_{i}^{\left(x_{2}\right)} \cdots \lambda_{i}^{\left(x_{v}\right)}=\lambda_{i}, \quad 0 \leq i \leq r,
$$

be the content decomposition of $\lambda_{i}$ and let

$$
\left\{\beta_{n 1}, \ldots, \beta_{n, s_{n}}\right\}, \quad 2 \leq n \leq v,
$$

be a standard GCD-free basis for $\left\{\lambda_{0}^{\left(x_{n}\right)}, \ldots, \lambda_{r}^{\left(x_{n}\right)}\right\}$. We assume that for all $2 \leq n \leq v$
i) $\quad \operatorname{deg}_{x_{n}}\left(\lambda_{i}\right)=\operatorname{deg}_{x_{n}}\left(\lambda_{i}\left(a_{2 \ldots n-1}, x_{n}, a_{n+1 \ldots \nu}\right)\right)$ for all $0 \leq i \leq r$,
ii) $\quad \lambda_{0}\left(a_{2 \ldots n-1}, x_{n}, a_{n+1 \ldots v}\right) \sim \operatorname{cont}_{x_{1}}\left(f\left(x_{1}, a_{2 \ldots n-1}, x_{n}, a_{n+1 \ldots v}\right)\right)$,
iii) $\quad\left(\operatorname{GCD}\left(\beta_{n i}, \beta_{n j}\right)\right)\left(x_{n}, a_{n+1 \ldots \nu}\right) \sim \operatorname{GCD}\left(\beta_{n i}\left(x_{n}, a_{n+1 \ldots v}\right), \beta_{n j}\left(x_{n}, a_{n+1 \ldots v}\right)\right)$ for all $1 \leq i<j \leq$ $s_{n}$.

Second, we assume that the calls to Sparse Lifting in step 3 return the correct results. Notice that the true factors assumption is guaranteed already by previous assumptions.

Output: $h_{0}, l_{1}, \ldots, l_{r} \in F\left[x_{2}, \ldots, x_{n}\right]$ such that $h_{0} \sim \operatorname{cont}_{x_{1}}(f)$ and $l_{i}=\operatorname{ldcf}_{x_{1}}\left(h_{i}\right), 1 \leq i \leq r$. Furthermore, $g_{12}, \ldots, g_{r 2} \in F\left[x_{1}, x_{2}\right]$ such that $g_{i 2}=h_{i}\left(x_{1}, x_{2}, a_{3 \ldots v}\right), 1 \leq i \leq r$.

Step 1: This step drives the iteration.
Initialization: $l \leftarrow \operatorname{ldcf}_{x_{1}}(f) ; l_{i} \leftarrow 1$ for $i=0, \ldots, r$.
FOR $n \leftarrow 2, \ldots, v$ WHILE $l \notin F$ DO

$$
\begin{array}{ll}
\text { IF } \operatorname{deg}_{x_{n}}(l)>0 \text { THEN } & \text { Perform step } 2 . \\
& \text { IF } I \neq \varnothing \text { THEN perform step } 3 .
\end{array}
$$

Step 2: At this point the following is always true.

$$
l_{i} \sim \prod_{j=2}^{n-1} \lambda_{i}^{\left(x_{j}\right)}, \quad 0 \leq i \leq r, \quad l \sim \frac{\operatorname{ldcf}_{x_{1}}(f)}{l_{0} l_{1} \cdots l_{r}} .
$$

Lift $\tilde{f}\left(x_{1}, x_{n}\right)=f\left(x_{1}, a_{2 \ldots n-1}, x_{n}, a_{n+1 \ldots \nu}\right)$ into $\tilde{g_{0}}, \ldots, \tilde{g}_{r} \in F\left[x_{1}, x_{n}\right]$ such that

$$
\tilde{g}_{0}=\operatorname{cont}_{x_{1}}(\tilde{f}), \quad \tilde{g}_{i}\left(x_{1}, a_{n}\right)=g_{i}, 1 \leq i \leq r, \quad \tilde{g}_{0} \tilde{g}_{1}^{e_{1}} \cdots \tilde{g}_{r}^{e_{r}}=\tilde{f}
$$

This amounts to a standard lifting step (see remark 2 below for improvements).
IF $n=2$ THEN set $g_{i 2} \leftarrow \tilde{g_{i}}$ for $i=1, \ldots, r$.
Compute the images of $\lambda_{i}^{\left(x_{n}\right)}$ :
FOR $i \leftarrow 0, \ldots, r$ DO

$$
\begin{array}{ll}
\text { IF } \operatorname{deg}_{x_{n}}\left(l_{i}\right)>0 & \text { THEN } \tilde{l}_{i} \leftarrow \operatorname{ldcf}_{x_{1}}\left(\tilde{g}_{i}\right) / l_{i}\left(a_{2 \ldots n-1}, x_{n}, a_{n+1 \ldots v}\right) \\
& \text { ELSE } \tilde{l}_{i} \leftarrow \operatorname{ldcf}_{x_{1}}\left(\tilde{g_{i}}\right) .
\end{array}
$$

At this point

$$
\tilde{l}_{i} \sim \lambda_{i}^{\left(x_{n}\right)}\left(x_{n}, a_{n+1 \ldots v}\right), \quad \operatorname{deg}_{x_{n}}\left(\tilde{l}_{i}\right)=\operatorname{deg}_{x_{n}}\left(\lambda_{i}^{\left(x_{n}\right)}\right), \quad 0 \leq i \leq r .
$$

Set $I=\left\{i_{1}, \ldots, i_{m}\right\} \subset\{0, \ldots, r\}$ such that $i \in I$ iff $\tilde{l}_{i} \notin F$.
Step 3: Find a standard GCD-free basis $\left\{\tilde{b}_{1}, \ldots, \tilde{b}_{s}\right\}$ for $\left\{\tilde{l}_{i}\right\}_{i \in I}$. Let $e_{0}=1$ and $\tilde{l}_{i}=\prod_{j=1}^{s} \tilde{b}_{j}^{u_{i j}}, 0 \leq$ $i \leq r$.

Call Sparse Lifting recursively with

$$
c l=\prod_{j=1}^{s} \tilde{b}_{j}^{\left(\Sigma_{i \in l} e_{i} u_{i j}\right)} \bmod \left(x_{n+1}-a_{n+1}, \ldots, x_{v}-a_{v}\right)
$$

where $c \in F$ is properly determined. The polynomials $b_{0}, b_{1}, \ldots, b_{s}$ are returned.
Set $l \leftarrow b_{0} ; l_{i} \leftarrow l_{i} \times \prod_{j=1}^{s} b_{j}^{u_{i j}}$ for all $i \in I$.
Step 1 cont.: Adjust outputs:
$l_{0} \leftarrow l_{0} / l_{0}\left(a_{2 \ldots \nu}\right)$. FOR $i \leftarrow 1, \ldots, r$ DO $l_{i} \leftarrow l_{i} \operatorname{ldcf}\left(g_{i}\right) / l_{i}\left(a_{2 \ldots \nu}\right)$.
Return $h_{0} \leftarrow l_{0}, l_{1}, \ldots, l_{r}, g_{l 2}, \ldots, g_{r 2}$.
Remark 1: In step 2 we must compute the factorization of $\tilde{f}\left(x_{1}, x_{n}\right)$. This amounts to lifting

$$
g_{1}^{e_{1}} \cdots g_{r}^{e_{r}} \equiv \tilde{f}\left(x_{1}, x_{n}\right) \bmod \left(x_{n}-a_{n}\right)
$$

similarly to step 4 of the Sparse Hensel Lifting algorithm. However, the content $\tilde{g}_{0}$ and the leading coefficients of $\tilde{g_{i}}$ are unknown and we must use special tricks. The following approach, that adapts Wang's [17] early factor detection algorithm in substep 3, appears to be the most efficient.

Substep 1: Compute $\tilde{g_{0}}=\operatorname{cont}_{x_{1}}(\tilde{f}), \tilde{f}^{\left(x_{1}\right)}\left(x_{1}, x_{n}\right)$ and the squarefree factorizations

$$
\frac{g_{i}}{\operatorname{ldcf}\left(g_{i}\right)}=g_{i 1} g_{i 2}^{2} \cdots g_{i, t_{i}}^{t_{i}}, g_{i j} \text { monic }, 1 \leq i \leq r
$$

by univariate GCD computations. Furthermore, compute the squarefree part $\bar{f}\left(x_{1}, x_{n}\right)$ of $\tilde{f}^{\left(x_{1}\right)}\left(x_{1}, x_{n}\right)$ by a bivariate GCD computation. Here we must assume that we can effectively determine $p$-th roots in case $F$ has characteristic $p>0$.

Substep 2: Lift

$$
\operatorname{ldcf}_{x_{1}}\left(\tilde{f}\left(x_{1}, y+a_{n}\right)\right) \prod_{i=1}^{r} \prod_{j=1}^{t_{i}} g_{i j} \equiv \bar{f}\left(x_{1}, y+a_{n}\right) \bmod y
$$

such that the lifted $g_{i j}^{(k)} \in F[x, y]$ remain monic in $x_{1}$ and are of sufficiently high degree $k$ in $y$ (see substep 3).

Substep 3: The $g_{i j}^{(k)}$ correspond to true factors $\tilde{g}_{i j} / l_{i j}, \tilde{g}_{i j} \in F[x, y], l_{i j} \in F[y]$, of $\bar{f}\left(x_{1}, y+a_{n}\right)$ in $F(y)[x]$. Let

$$
g_{i j}^{(k)}=x^{d}+\gamma_{d-1}(y) x^{d-1}+\cdots+\gamma_{0}(y), \quad \gamma_{m}(y) \in F[y] .
$$

For $0 \leq m \leq d-1$ compute $p_{m}(y) / q_{m}(y)$, the highest order Padé approximation for $\gamma_{m}(y) / y^{k}$. We refer to Czapor and Geddes [4] for a comparison of several Padé approximation algorithms. Set $l_{i j} \leftarrow \operatorname{LCM}_{0 \leq m \leq d-1}\left(q_{m}(y)\right)$. Notice that in practice a few $m$ will already determine the $l_{i j}$ correctly. Also, the degree bound $k$ depends on $\operatorname{deg}\left(l_{i j}\right)$ and thus the $\tilde{g}_{i j}$ are correctly detected at different lifting levels $k$.
Return $\tilde{g}_{0}, \tilde{g}_{i} \leftarrow \prod_{j=1}^{t_{i}} \tilde{g}_{i j}^{j}\left(x_{1}, x_{n}-a_{n}\right)$.
Notice that the above method might fail under two different circumstances, namely when the squarefree factorization of $g_{i}$ is not a true image of that of $\tilde{g}_{i}$ and when the GCD of $\gamma_{m}$ and $y^{k}$ is of too high a degree. We leave it to the reader to establish the conditions for $a_{n}$ such that no failure can occur. For randomly chosen $a_{n}$ this turns out to be very rare. The reason why we suggest the squarefree factorization in substep 1 whereas we do not unconditionally use it in the Sparse Hensel Lifting algorithm (see also remark 1 following the algorithm) is because in the bivariate case the size of the lifting problem is certainly reduced.

Remark 2: In step 1 we processed the minor variables in the order of their subscripts. This order may by no means be optimal and in practice it appears better to process the minor variable of maximum individual degree first. It should also be clear that the Leading Coefficient algorithm applies for the pre-determination of trailing coefficients as well. We recommend to employ this additional process in step 1 of the Sparse Lifting algorithm if the trailing coefficient of $f$ has many monomials. Then the linear systems of step 5.4 have a greatly reduced number of unknowns.

Remark 3: In step 3 we not only need the standard GCD-free basis $\left\{\tilde{b}_{1}, \ldots, \tilde{b}_{s}\right\}$ of $\left\{\tilde{l}_{i}\right\}$ but also the exponent vectors $u_{i, 1 . . . s}$. It is, however, an easy modification of the Standard GCD-Free Basis algorithm to compute the vectors along with the $c_{t+1}$. Again the details are left to the reader.

We now establish the correctness of the leading coefficient algorithm.
Theorem 5.1: The true factors and true leading terms assumptions imply that the true factors assumption is satisfied for the (first level) calls from the Leading Coefficient Determination algorithm to the Sparse Hensel Lifting algorithm. Moreover, the correct content and leading coefficients are computed provided that the recursive calls have also returned the correct results.

## 6. Analysis

We first establish a general condition under which all except the true factors assumption are satisfied.

Theorem 6.1: Consider the sparse Hensel lifting algorithm with the provision that the true factors assumption is satisfied. Let $d=\operatorname{deg}\left(h_{0} \cdots h_{r}\right)$. The there exists a polynomial $\pi^{\left(h_{0 . \ldots r}\right)}\left(x_{2 \ldots v}\right)$ $\in F\left[x_{2 \ldots . .}\right]$ such that

$$
\operatorname{deg}\left(\pi^{\left(h_{0 . \ldots r}\right)}\right)<v(2 d+2)^{v+1}
$$

and $\pi^{\left(h_{0 . \ldots r}\right)}\left(a_{2 \ldots \nu}\right) \neq 0$ implies that the algorithm returns the correct results.
It now follows from a lemma by Schwartz [13] that if we select the $a_{i}$ randomly from a set with ( $\operatorname{deg} \pi^{\left(h_{0 . \ldots r}\right)}$ ) $\varepsilon$ elements then the probability that $\pi^{\left(h_{0 . \ldots r}\right)}\left(a_{2 \ldots v}\right)=0$ becomes less then $\varepsilon$. It should be noted, however, that the very high degree bound of theorem 6.1 is only of theoretical interest. First, because if all intermediately computed $h_{i}$ are sparse, the bound is much smaller. Second, because even if the degree of $\pi^{\left(h_{0 . . r}\right)}$ is of the same order as our estimate, the chance that we select a zero point of $\pi^{\left(h_{0 . . r}\right)}$ is, in practice, much smaller than $\varepsilon$.

The correctness of the true factors assumption must be imported into our algorithm. In factorization applications effective Hilbert irreducibility theorems are needed, cf. von zur Gathen [6] and Kaltofen [8]. For GCD applications conditions guaranteeing the true factors assumption are not as difficult to find (see theorem 7.1).

We wish to point out that our sparse Hensel lifting algorithm can have super-polynomial expected running time in the number of monomials of the result. The reason is that dense factors might accumulate in $l_{i}$ during the execution of the leading coefficient determination algorithm, e.g., if

$$
\lambda_{i}=\prod_{i=2}^{v}\left(\sum_{j=0}^{d} x_{i}^{j}\right),
$$

or that the $b_{j}$ might be dense while the $l_{i}$ are not. An example for this case is

$$
r=2, \lambda_{0}=1, \lambda_{1}=\prod_{i=3}^{v}\left(x_{2}^{d}-x_{i}^{d}\right), \lambda_{2}=\prod_{i=3}^{v}\left(x_{2}-x_{i}\right),
$$

where $\operatorname{mon}\left(\lambda_{1}\right)=\operatorname{mon}\left(\lambda_{2}\right)=2^{\nu-2}$ but $\operatorname{mon}\left(\lambda_{1} / \lambda_{2}\right)=d^{\nu-2}$. The remedy for this problem is to choose evaluations

$$
x_{2}=a_{2}+b_{2} x_{1}, \ldots, x_{v}=a_{v}+b_{v} x_{1}, \quad a_{i}, \quad b_{i} \in F,
$$

which were first employed by Viry [14] for a different purpose. It is then very likely (again the $a_{i}$ and $b_{i}$ must not be zeros of certain polynomials) that the following conditions are satisfied:
i) $\quad \operatorname{deg}_{x_{1}}\left(f\left(x_{1}, a_{2}+b_{2} x_{1}, \ldots, a_{v}+b_{v} x_{1}\right)\right)=\operatorname{deg}(f)$,
ii) $\quad \operatorname{ldcf}_{x_{1}}\left(h_{i}\left(x_{1 \ldots n-1}, \quad a_{n}+b_{n} x_{1}+y, \quad a_{n+1}+b_{n+1} x_{1}, \ldots, \quad a_{v}+b_{v} x_{1}\right)\right)=\operatorname{ldcf}_{x_{1}}\left(h_{i}\left(x_{1 \ldots n-1}\right.\right.$, $\left.\left.a_{n}+b_{n} x_{1}, \ldots, a_{v}+b_{v} x_{1}\right)\right), 1 \leq i \leq r, 2 \leq n \leq v$.

Condition i) implies that the image of $\operatorname{cont}_{x_{1}}(f)$ occurs among the $g_{i}$ with

$$
\prod_{i=1}^{r} g_{i}^{e_{i}}=f\left(x_{1}, a_{2}+b_{2} x_{1}, \ldots, a_{v}+b_{v} x_{1}\right)
$$

If we now lift this factorization with the Sparse Hensel lifting algorithm we do not need the leading coefficient algorithm at all due to condition ii). We must modify step 5.1 such that all $c_{i}^{\left(j_{1} \ldots n-1\right)}$ are considered with $j_{1} \leq \operatorname{deg}_{x_{1}}\left(g_{i, n-1}\right)$ and such that the monomial $x_{1}^{j_{1}} x_{2}^{j_{2}} \cdots x_{n-1}^{j_{n-1}}$ has a nonzero coefficient in $g_{i, n-1}$ for some $j_{1}^{\prime}$. Also, $g_{i, n}$ is set to $g_{i, n}^{(k+1)}\left(x_{1 \ldots n-1}, x_{n}-b_{n} x_{1}-a_{n}\right)$ at the end of step 4. This translation will force the correct leading coefficient on $g_{i, n+1}^{(k)}$ for all $k$ by condition ii). We hope that this brief sketch is sufficient for the reader to fill in the details.

We remark that these modification result in an algorithm very similar to, but more efficient, than von zur Gathen's [7]. The gain in efficiency is achieved by our Hilbert irreducibility theorem [8] that allows us to use substitutions of the type $(\dagger$ ) (see also [11]). However, any such substitutions may lead to a substantial increase in complexity unless we are dealing with a pathological case as mentioned above. First, we will have to process a univariate polynomial of degree $\operatorname{deg}(f)$ rather than $\operatorname{deg}_{x_{1}}(f)$. Second, and more significantly, the modification generates intermediate polynomials dense in the two variables $x_{1}$ and $y$, thus approximately squaring the number of intermediate monomials. In von zur Gathen's algorithm the intermediate polynomials are dense in even three variables.

## 7. Application: The Sparse EZ-GCD Algorithm

We now discuss how we can apply our sparse lifting algorithm to computing GCDs of sparse polynomials. We follow Moses's and Yun's [12] E(xtended) - Z(assenhaus) - GCD approach but incorporate several important changes. First, we do no compute the primitive parts of the inputs by recursive application of the GCD algorithm. This saves us the task of computing the GCD of many polynomials in one less variables, namely the coefficients of the inputs with respect to the main variable. Second, we do not impose any leading coefficient upon the image GCD before lifting, but determine the correct leading coefficient by our leading coefficient algorithm. The overall improvement to the EZ-GCD algorithm is a substantial reduction in the number of uni- and multivariate GCD operations performed. It should be clear that the reference to the Sparse Lifting algorithm by itself speeds up the EZ-GCD process. One major advantage is, as we shall see below, that we can lift factors with higher multiplicities. We remark that Wang [16] also suggests assorted improvements to the EZ-GCD algorithm, most significantly the leading coefficient predetermination method. Since Wang had such a method only for integral coefficients, this of his improvements to the EZ-GCD algorithm was necessarily restricted to the integral case.

## Sparse EZ-GCD algorithm

Input: $f_{1}, \ldots, f_{r} \in F\left[x_{1 \ldots v}\right], F$ a field, $a_{1}, \ldots, a_{v} \in F$ and $g \in F\left[x_{1}\right] \backslash F$ such that

$$
\operatorname{ldcf}_{x_{1}}\left(f_{1} \cdots f_{r}\right)\left(a_{2 \ldots v}\right) \neq 0 \text { and } g=\operatorname{GCD}_{1 \leq i \leq r}\left(f_{i}\left(x_{1}, a_{2 \ldots v}\right)\right)
$$

We make the following assumptions on $a_{1}, \ldots, a_{v}$ :
True $G C D$ assumption: Let $h=\operatorname{GCD}_{1 \leq i \leq r}\left(f_{i}\right)$. Then $h\left(x_{1}, a_{2 \ldots v}\right) \sim g$.
True cofactor assumption: Let $\left\{b_{1}, \ldots, b_{s}\right\}$ be a standard GCD-free basis for $\left\{f_{1}^{\left(x_{1}\right)}, h^{\left(x_{1}\right)}\right\}$. We assume that

$$
\operatorname{GCD}\left(b_{i}, b_{j}\right)\left(x_{1}, a_{2 \ldots v}\right) \sim \operatorname{GCD}\left(b_{i}\left(x_{i}, a_{2 \ldots v}\right), b_{j}\left(x_{1}, a_{2 \ldots v}\right)\right) \text { for all } 1 \leq i<j \leq s
$$

True content assumption: We assume that
$\operatorname{GCD}\left(\operatorname{cont}_{x_{1}}\left(f_{1}\right), f_{2}\left(a_{1}, x_{2 \ldots v}\right), \ldots, f_{r}\left(a_{1}, x_{2 \ldots \nu}\right)\right)=\operatorname{cont}_{x_{1}}(h)$.
Finally, we assume that the calls to Sparse Lifting and the recursive calls to Sparse EZ-GCD return the correct results. Notice, however, that the true factors assumption for the call to Sparse Lifting follows from assumptions already made.

Output: $h \in F\left[x_{1 \ldots . v}\right]$ such that $h\left(x_{1}, a_{2 \ldots .}\right)=g$ and $h \sim \operatorname{GCD}_{1 \leq i \leq r}\left(f_{i}\right)$. Notice that $h$ is uniquely determined.

Step 1: Compute a standard GCD-free basis $\left\{\tilde{b}_{1}, \ldots, \tilde{b}_{s}\right\}$ for $\left\{\tilde{f}_{1}\left(x_{1}\right)=f_{1}\left(x_{1}, a_{2 \ldots v}\right), g\right\}$. Let $d_{j}$, $e_{j}, 1 \leq j \leq s$ be such that $\tilde{f}_{1}=\prod_{j=1}^{s} \tilde{b}_{j}^{d_{j}}, g=\prod_{j=1}^{s} \tilde{b}_{j}^{e_{j}}$.

Call Sparse Lifting with

$$
f_{1} \equiv \prod_{j=1}^{s} \tilde{b}_{j}^{d_{j}} \bmod \left(x_{2}-a_{2}, \ldots, x_{v}-a_{v}\right) .
$$

The polynomials $b_{0}=\operatorname{cont}_{x_{1}}\left(f_{1}\right), b_{1}, \ldots, b_{s}$ are returned.
Set $h^{\left(x_{1}\right)} \leftarrow \prod_{j=1}^{s} b_{j}^{e_{j}}$.
Step 2: Compute

$$
\tilde{g}=\operatorname{GCD}\left(b_{0}\left(x_{2}, a_{3 \ldots \nu}\right), f_{2}\left(a_{1}, x_{2}, a_{3 \ldots v}\right), \ldots, f_{r}\left(a_{1}, x_{2}, a_{3 \ldots \nu}\right)\right)
$$

by a univariate GCD algorithm (see remark 2).
Call Sparse EZ-GCD recursively with

$$
b_{0}, f_{2}\left(a_{1}, x_{2 \ldots v}\right), \ldots, f_{r}\left(a_{1}, x_{2 \ldots v}\right) \text { and } \tilde{g}
$$

The polynomial $\bar{h} \in F\left[x_{2 \ldots \nu}\right]$ is returned.
Step 3: Adjust output: Set $h \leftarrow \bar{h} h^{\left(x_{1}\right)}$.
Return $h \leftarrow \operatorname{ldcf}(g) / \operatorname{ldcf}_{x_{1}}(h)\left(a_{2 \ldots v}\right) h$.
Remark 1: We arbitrarily chose $f_{1}$ for the lifting process. However, it can be more efficient to select the polynomial with the fewest terms among the $f_{i}$ in place of $f_{1}$.

Remark 2: To provide the input $g$ and to compute $\tilde{g}$ requires a univariate GCD computation of $r$ polynomials. It can be shown that with high probability

$$
\operatorname{GCD}\left(g_{1}, \ldots, g_{r}\right)=\operatorname{GCD}\left(\sum_{i=1}^{r} \lambda_{i} g_{i}, \sum_{i=1}^{r} \mu_{i} g_{i}\right)
$$

for $g_{1}, \ldots, g_{r} \in F[x], \lambda_{1}, \ldots, \lambda_{r}, \mu_{1}, \ldots, \mu_{r} \in F$ randomly selected (cf. [10], Theorem 5.2). This observation probabilistically reduces the problem to a single univariate GCD computation. We should add that the univariate GCD problem over $\mathbf{Q}$ can also be solved by the EZ-GCD algorithm. The process of lifting with multiplicities still applies because the true factors assumption can be enforced under these special circumstances.

Remark 3: If one of the assumptions is violated, the algorithm might return an incorrect result. We can, however, check whether $h$ divides $f_{2}, \ldots, f_{r}$. If that is so $h$ is guaranteed to be the correct GCD. In order to perform the sparse polynomial division we can make use of Sparse Lifting again, similarly to the Sparse EZ-GCD algorithm. This check will also produce the co-factors.

We now carry out the analysis.
Theorem 7.1: Let $d=\max \left\{\operatorname{deg}\left(f_{i}\right) \mid 1 \leq i \leq r\right\}$. Then there exist a polynomial $\rho^{\left(f_{1 \ldots r}\right)}\left(x_{1 \ldots v}\right) \in$ $F\left[x_{1 \ldots v}\right]$ such that

$$
\operatorname{deg}\left(\rho^{\left(f_{1 . . r}\right)}\right)<\left(v^{2}+1\right)(2 d+2)^{v+1}
$$

and $\rho^{\left(f_{1 \ldots r}\right)}\left(a_{1 \ldots v}\right) \neq 0$ implies that all assumptions to the Sparse EZ-GCD algorithm are satisfied.
One final remark is in order. The Sparse EZ-GCD algorithm does not run in expected polynomial-time in the size of the inputs and outputs for similar reasons as the ones given in §6 for the Sparse Lifting algorithm. However, the problems cannot be overcome by merely introducing a different evaluation. The problem is that we are forced to compute a GCD-free basis before lifting. Our results in [10] have as a consequence a polynomial-time solution for the sparse GCD problem.

## 8. Conclusion

Our results hopefully put the last of the problems for sparse multivariate lifting, the leading coefficient problem, to rest. We have also established, by example of the sparse EZ-GCD algorithm, that content computations can be avoided prior to the lifting process. Finally we have introduced the notion of standard GCD-free basis and made precise its critical-pair completion construction, a process that has been used in the folklore of computer algebra in the past.

Our formulation of the Newton-Hensel Lemma has helped us to simplify the proof of the Main Theorem of Sparse Lifting. The full power of this approach becomes most apparent when applying it to factoring polynomials given by straight-line programs, such as polynomial determinants. In [10] and [11] we begin to develop a theory for computing with polynomials given by straight-line programs and established as one of the major results an expected polynomial-time procedure for factoring a polynomial given by a straight-line program into its sparse factors.

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